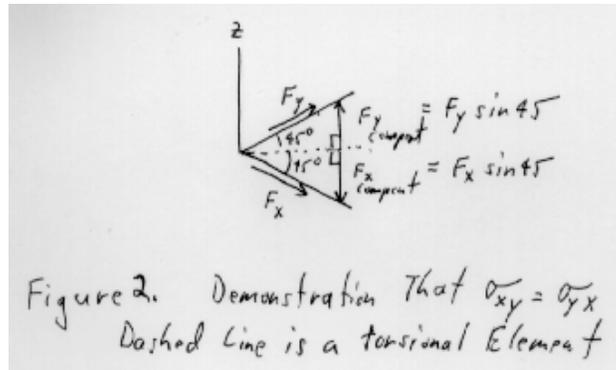


Quiz 1 Mechanics of Materials  
020930

- 1) a) Demonstrate that  $\tau_{12} = \tau_{21}$  by making a sketch of a Cartesian coordinate system with two shear stresses and a torsional element located midway between the two shear stresses.
- b) What assumptions are necessary for this equality to be true?
- 2) a) Show that  $\frac{1}{2}(\tau_{ik} \tau_{ki} - \tau_{ii} \tau_{kk}) = \begin{vmatrix} 22 & 23 \\ 32 & 33 \end{vmatrix} + \begin{vmatrix} 11 & 13 \\ 31 & 33 \end{vmatrix} + \begin{vmatrix} 11 & 12 \\ 21 & 22 \end{vmatrix}$  by expanding the determinates and expanding the summations.
- b) What quantity do these expressions describe.
- c) What is an invariant?
- 3) a) How many independent components are there in the stress tensor?
- b) How many independent components are there in the following tensors:  
 Displacement tensor,  $e_{ij}$   
 strain tensor,  $\epsilon_{ij}$   
 rotational tensor,  $\omega_{ij}$
- c) If the stress is related to strain through a tensoral modulus,  $\sigma_{ij} = C_{ijkl} \epsilon_{kl}$ , how many components would this generic modulus have?

Answers: Quiz 1 Mechanics of Materials

1) a) This can be demonstrated for one pair of symmetric shear stresses, for instance  $\tau_{xy}$  and  $\tau_{yx}$ , Figure 2. The dashed line in figure 2 is a torsional bar which must have not rotational torque is the system is not subjected to rotational motion. Two stresses,  $\tau_{xy}$  and  $\tau_{yx}$ , are applied to the system. The torsional element is subjected to two rotational forces shown. These two forces must balance under these conditions leaving  $F_y = F_x$  and  $\tau_{xy} = \tau_{yx}$ . (For each off diagonal torsional element the solid body has two symmetric torsional elements which when summed lead to the same result.)



b) Assumptions: No rotational torque on the material.

$$2) \ a) \ \frac{1}{2} (\tau_{ik} \tau_{ki} - \tau_{ii} \tau_{kk}) = \begin{vmatrix} 22 & 23 \\ 32 & 33 \end{vmatrix} + \begin{vmatrix} 11 & 13 \\ 31 & 33 \end{vmatrix} + \begin{vmatrix} 11 & 12 \\ 21 & 22 \end{vmatrix}$$

For the Einstein notation expression:

$$\frac{1}{2} (\tau_{11} \tau_{11} - \tau_{11} \tau_{11} + \tau_{12} \tau_{21} - \tau_{11} \tau_{22} + \tau_{13} \tau_{31} - \tau_{11} \tau_{33}) + (\tau_{21} \tau_{12} - \tau_{22} \tau_{11} + \tau_{22} \tau_{22} - \tau_{22} \tau_{22} + \tau_{23} \tau_{32} - \tau_{22} \tau_{33}) + (\tau_{31} \tau_{13} - \tau_{33} \tau_{11} + \tau_{32} \tau_{23} - \tau_{33} \tau_{22} + \tau_{33} \tau_{33} - \tau_{33} \tau_{33}) = [ \tau_{12} \tau_{21} - \tau_{11} \tau_{22} + \tau_{13} \tau_{31} - \tau_{11} \tau_{33} + \tau_{23} \tau_{32} - \tau_{22} \tau_{33} ]$$

This is the negative of the determinate result (group each 2 terms and identify with the 3 determinates).

b) This is equal to  $I_{22}$ , the second invariant of the stress tensor.

c) An invariant is a magnitude (scalar) calculated from a tensor that does not vary with rotation of the coordinate system or conversion to a different coordinate system. A vector has one invariant, the magnitude of the vector. A second order tensor has 3 invariants.

3) a) The stress tensor has 6 independent components since it is a symmetric tensor.

b) Displacement tensor,  $e_{ij}$ , has 9 independent components.

strain tensor,  $\epsilon_{ij}$ , has 6 independent components since it is symmetric.

rotational tensor,  $\omega_{ij}$ , has 3 independent components since it is antisymmetric and the cross terms are 0.

c) The generic modulus would have 6x6 or 36 components.